

Automation Solutions

JAG MoMa Family

One common mobile platform, tailored to your mission



JAG MoMa Family

Typical applications



JAG MoMa 4

- » Equipped with a 4-axis collaborative robot, closed rotative storage (customizable with filter, cooling or heating air conditioning).
- » Perform sample handling between workbenches and different laboratories within the facility.
- » By linking small and large cold storage units, MoMa 4 enables a connected, flexible sample logistics network across the laboratory.
- » Designed for flexibility and adaptability, MoMa 4 can autonomously transport a wide variety of items. Up to 130×70×150 mm, across multiple environments.



JAG MoMa 6

- » Featuring a 6-axis cobot equipped with interchangeable, customizable grippers and an adaptable top module with modular tools and fixtures.
- » Empower your lab by bringing legacy, manual instruments into the automation era. Enhancing workflow efficiency without replacing existing assets.
- » E.g., Agilent HPLCs require intricate lid and plate handling, fully automated to streamline lab workflows.
- » Seamlessly automates complex workflows and interactions with multiple instruments and machines across a wide range of industries.

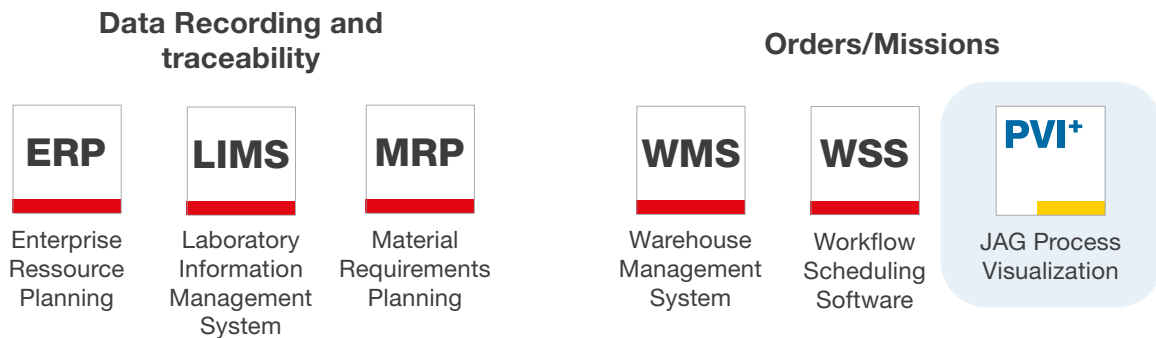


JAG MoMa LOG

- » Handles logistics flows between labs, production areas, and any point of need with full flexibility.
- » From wherever it's requested to wherever it's needed, moves trolleys, mobile cabinets, and boxes with ease.
- » Delivers equipment, reactants, ingredients, and consumables or simply collects waste.
- » Highly flexible and suitable for any industry, with custom-made trolleys tailored to your specific needs.

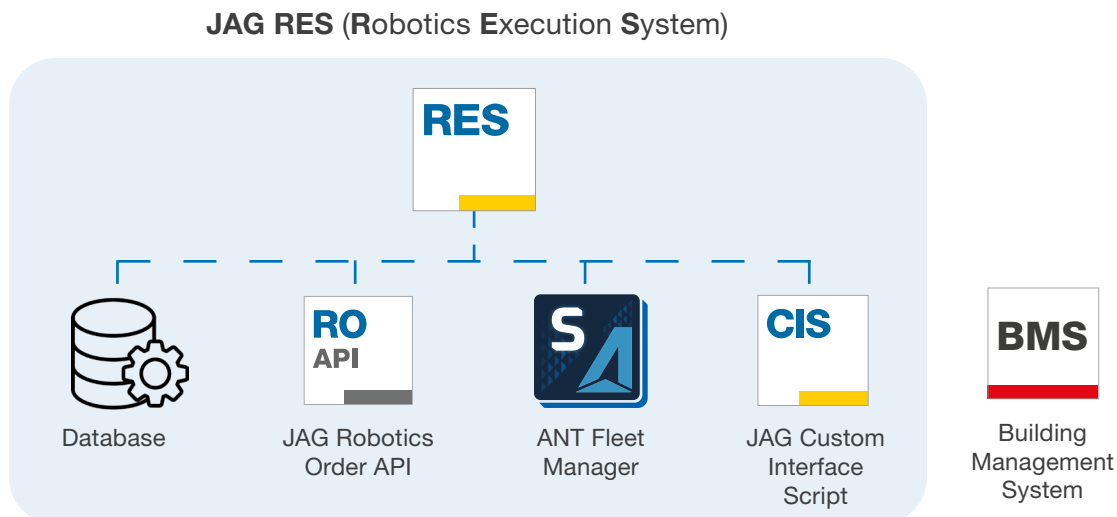
Integration Level 3

Integrating JAG's mobile robotics solutions into your management layer enables **seamless mission creation, comprehensive data traceability**, and **intelligent supervision** across all operational processes.



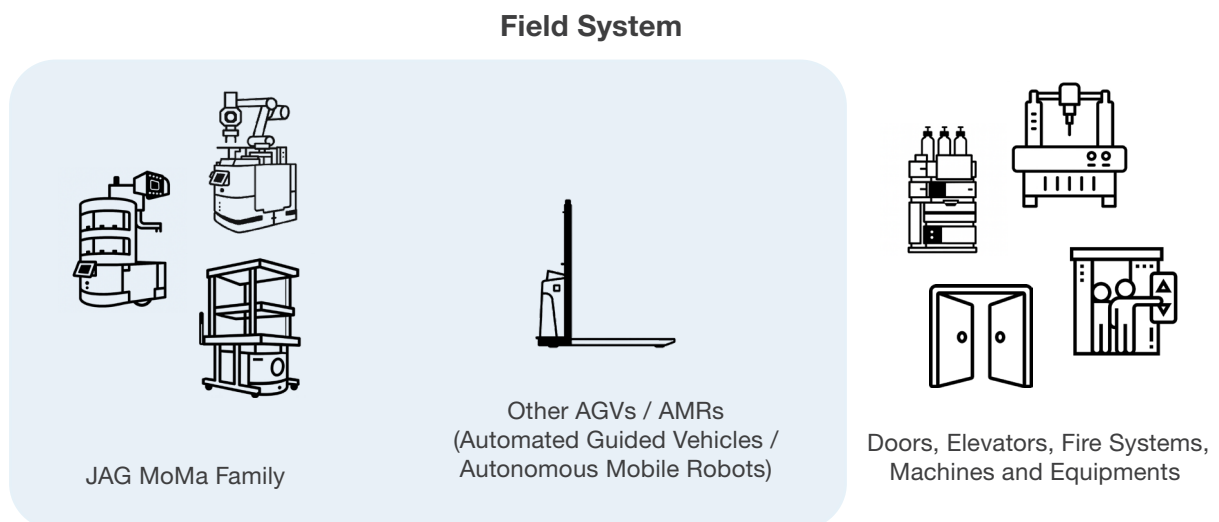
Integration Level 2

JAG Middleware enables a **seamless transition** between your existing systems and the interpretation required by our robotics solutions and physical equipment.



Integration Level 1

Operational execution is achieved through our mobile robotics solutions working in harmony with the connected physical infrastructure.



JAG MoMa Family datasheet

	JAG MoMa 4	JAG MoMa 6	JAG MoMa LOG
Dimensions	680 x 455 x 1700mm	750 x 579 x 1800mm	680 x 455 x 700mm
Certifications	2006/42/EC ISO 3691-4 ISO 13849 2014/30/EU 2014/35/EU IP10		
Vehicle	JAG MoMa Base		
Fleet Management	BlueBotics ANT Server		
Speed	Min. 0.1 m/s Max. 1.5 m/s		
Position accuracy	+/-10mm & +/-1°		
Navigation type	Virtual line following (AGV), Obstacle avoidance (AMR)		
Min. turning radius	0 m (the vehicle turns on the spot)		
Safety	360° LiDAR safety scanner		
Communication	WiFi - WLAN 802.11 a/b/g/n - 2.4/5GHz		
Charger	1 kW inductive (100-240VAC 50/60Hz max. 11.25A)		
Battery type	Lithium-ion with integrated BMS (Battery Management System)		
Battery energy / capacity	3 kWh / 116 Ah		
Autonomy	Up to 8h depending on application		
Charging time	From 20 to 80% in less than 2h		

Top Modules			
Manipulator	Brooks PF3400	ABB, Stäubli, Fanuc	Lift, conveyor
Degree of Freedom	4 axis	6 axis	1 axis or 2 axis
Payload capacity	3 kg	5kg/ 10kg up to 20kg	200 kg
Dynamic positioning correction	Vision-based	Vision-based	Dynamic trolley alignment
Operating range	X, Y 600 mm Z 750 mm	800, 1200 and up to 1620 mm	-
Operating accuracy	+/- 0.5mm	+/- 0.3mm	-
Gripper / Tools Top Module	SBS box gripper (130x70x150mm)	Tool changer with up to 4 grippers	-
On-board storage	Enclosed rotary storage	Modular tools and fixtures positions	Trolley, box, bag, equipment
Storage capacity	20 positions	Up to 6 positions	1 position
Obstacle detection at height	3D camera	3D camera	3D camera

¹ Maximum transit speed, conditionally possible on JAG MoMa's being equipped with the JAG AMR Safety Bubble option.

² Environment-adaptive, standard maximum transit speed for mixed human & AMR operational environments.

³ The Mission Point accuracy is the ensured precision of the Cobot/Manipulator for interacting with or delivering Sample Plates / Labware to/from the Instrument or storage.

As this accuracy is mainly dependent on the Lab bench Instrument's intrinsic positioning precision, it can be improved by customized 3D-sensing options.

⁴ The load capacity is the maximum overall, summed weight of the Gripper's weight and the Load's weight.

⁵ The maximum robotic arm reach must be assessed on a per-case basis, as it is dependent of the payload weight and on the presence of anti-tilting feet.

«Revolutionizing lab automation –
not just at the bench, but across your
entire laboratories and buildings.»

JAG Jakob AG

Industriestrasse 20
CH-2555 Brugg
T +41 32 374 30 30
jagpt@jag.ch
www.jag.ch

JAG Jakob AG

Rue de la Roche-de-Mars 12
CH-2900 Porrentruy
T +41 32 374 34 34
jagpt@jag.ch
www.jag.ch

